

- when it has to be **right** 

# Leica Geosystems Release Notes

Product	Leica Infinity
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From	Kevin Hanson

## Leica Infinity v4.2.1



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## TABLE OF CONTENTS

1	Welcome to Infinity v4.2.1	3
2	Installation Details	4
3	Tunnel Inspection – Compare Profiles From Point Clouds and Design Data	5
4	General Application Improvements and Fixes	6
5	What is New v4.2	7
6	Infrastructure Module	7
7	Point Cloud Registration Option	8
8	Point Clouds Module	8
9	Imaging Module	9
10	Features Module	10
11	Surfaces Module	10
12	General Application Improvements and Fixes	10



## 1 WELCOME TO INFINITY V4.2.1

Leica Infinity v4.2.1	Please read the following chapters carefully to learn more about what is new.
Overview What's New	<ul> <li>Tunnel Inspection tool to create and compare tunnel profiles from point clouds along a tunnel feature</li> <li>Support for Leica GS05 GNSS Smart Antenna</li> <li>Generate an orthophoto directly after a stored image group orientation</li> <li>Updated CLM package</li> <li>Quality improvements and bug fixes</li> </ul>
GETTING STARTED – HELP & SUPPORT	Getting started, users have access to information and useful data including coordinate systems, stylesheets, tutorials and sample data, all available from the <i>Localisation Tool</i> . From the <i>Help</i> menu, click on the <i>Localise your Infinity</i> button to access this data and the tutorials to help you get started with Infinity.
	Localise your Infinity Download Coordinate Systems from your country Get the latest Training Materials Download Stylesheets for Data Export
ORDERING INFINITY	Infinity has flexible ordering options. Users can purchase a one-time permanent perpetual license or can now also buy into a subscription plan.
	On top of our existing Leica Infinity – Basic package, users can also purchase additional packages depending on their needs. One of them now covers the new Point Cloud Registration option. All packages and their features can be found on the Leica Infinity data sheet.
	<u>Contact</u> your local Leica representative to discuss what options are best for meeting your project and workflow needs.
YouTube Videos	Check the Leica Infinity <u>YouTube page</u> to see our playlist of videos about new features and how-to-videos.



## 2 INSTALLATION DETAILS

INSTALLATION Leica Infinity v4.2.1 Build Maintenance End	d Date
INFORMATION 45798 1 <sup>st</sup> July 2024	1
Leica Infinity is available as a Windows 64bit only applica	ation
With an active CCP or Leica Infinity subscription license, u able to update to this new version. Confirm that your Main Date is on or after the date listed above before installation New users can download the latest version from the Leica Geosys support website.	users will be tenance End stems <u>myWorld</u>
CHECK FOR UPDATES From Help & About choose <b>Check for updates</b> . When a new version will be notified that the update can be downloaded from <u>myWorld</u> .	is available you
Get the latest updates available for Infinity	
OPERATING SYSTEM The following Microsoft <sup>®</sup> Windows <sup>™</sup> operating system editions are su	upported:
REQUIREMENTS • Windows 10 • Windows 11	
Note: you must have administrative privileges on your computer install Leica Infinity.	to successfully
MINIMUM HARDWARE • Display: 1024 * 768 px	
Input: keyboard and mouse with wheel	
Processor: multi-core 2.4 GHz	
RAM: 8 GB     Disk storage: 100 CP	
<ul> <li>Disk storage. 100 GB</li> <li>Graphics: DirectX9 compatible</li> </ul>	
RECOMMENDED - Dual Display: 1020 * 1280 py	
HARDWARE Input: keyboard and mouse with wheel	
<ul> <li>HARDWARE</li> <li>Input: keyboard and mouse with wheel</li> <li>Processor: multi-core 3.5 GHz or more</li> </ul>	
<ul> <li>HARDWARE</li> <li>Input: keyboard and mouse with wheel</li> <li>Processor: multi-core 3.5 GHz or more</li> <li>RAM: 32 GB or more</li> </ul>	
<ul> <li>HARDWARE</li> <li>Input: keyboard and mouse with wheel</li> <li>Processor: multi-core 3.5 GHz or more</li> <li>RAM: 32 GB or more</li> <li>Disk storage: SSD of 1 TB or more</li> </ul>	
<ul> <li>HARDWARE</li> <li>Input: keyboard and mouse with wheel</li> <li>Processor: multi-core 3.5 GHz or more</li> <li>RAM: 32 GB or more</li> <li>Disk storage: SSD of 1 TB or more</li> <li>Graphics: DirectX11 compatible, 8 GB memory or more, CUDA or</li> </ul>	capable
HARDWARE       Input: keyboard and mouse with wheel         Processor: multi-core 3.5 GHz or more         RAM: 32 GB or more         Disk storage: SSD of 1 TB or more         Graphics: DirectX11 compatible, 8 GB memory or more, CUDA comparison         RECOMMENDED	capable
HARDWARE       Input: keyboard and mouse with wheel         Processor: multi-core 3.5 GHz or more         RAM: 32 GB or more         Disk storage: SSD of 1 TB or more         Graphics: DirectX11 compatible, 8 GB memory or more, CUDA or         RECOMMENDED         HARDWARE FOR	capable
HARDWARE       Input: keyboard and mouse with wheel         Processor: multi-core 3.5 GHz or more         RAM: 32 GB or more         Disk storage: SSD of 1 TB or more         Graphics: DirectX11 compatible, 8 GB memory or more, CUDA comparison         RECOMMENDED         HARDWARE FOR         Imput: keyboard and mouse with wheel         Processor: 8 Core 3.5 GHz or more         Processor: 8 Core 3.5 GHz or more	capable
HARDWARE       Input: keyboard and mouse with wheel         Processor: multi-core 3.5 GHz or more         RAM: 32 GB or more         Disk storage: SSD of 1 TB or more         Graphics: DirectX11 compatible, 8 GB memory or more, CUDA c         RECOMMENDED         HARDWARE FOR         Input: keyboard and mouse with wheel         Input: keyboard and mouse with wheel         Processor: 8 Core 3.5 GHz or more         POINT CLOUD         Processor: 8 Core 3.5 GHz or more         Dual Display: 1920 * 1280 px         HARDWARE FOR         INPUt: keyboard and mouse with wheel         Processor: 8 Core 3.5 GHz or more         Point CLOUD         RAM: 64 GB or more, XMP enabled         Disk storage: SCD of 2TD enumer	capable



#### 3 TUNNEL INSPECTION – COMPARE PROFILES FROM POINT CLOUDS AND DESIGN DATA



New for tunnel construction workflows, create profiles from point clouds and compare to a tunnel design is now available using the Tunnel Inspection tool.

The generated profiles are stored as part of a Tunnel Inspection object and can be viewed in cross-section and 3D views. The inspection results include deviations (profile offsets), volumes and user defined tolerance statistics. The results can be exported to CAD or saved to a PDF as a printable report.



Create Tunnel Inspection	The Create Tunnel Inspection lets you compare	🖺 New Tunnel Insp	ection	
	point cloud data to a tunnel design material surface.	▲ Feature		
	point oloud data to a tannoi doolgii matonai oundoo.	Tunnel Inspection Id	E-Line Inspection	1
		Date/Time		25-09-2024 19:27:31
	The length of increation is configured by eatting the	Source	User-entered	
	The length of inspection is configured by setting the	→ Input		
	start and end chainage such as to generate reports	Tunnel Id	E110 Tunnel	/
		Reference Type	Surface	
	between a tunnel segment.	Reference Feature	E-Line Design	G /
	-	Target Type	Point Cloud	-
		Target Feature	Scan 1	6 /
	Set the profile extraction interval to consider the	Start Chainage		116+000.000 m
		End Chainage		116+500.000 m
	number of profiles to be created, including the point	Length		500.0000 m
	of interests along the alignment	A Profile Generation	i i	
	or interests along the alignment.	Chainage Interval		10.0000 m
		Include Horizontal POI		
		Include Vertical POI		
	Use point cloud slicing settings to best consider the	Scan Definition	Vertical	•
	point aloud data to be used for profile generation	A Point Cloud Slicin	3	
	point cioud data to be used for profile generation.	Slicing Plane Thickness		0.0100 m
		Discard Sparse Points		1.0000 m
		Reduce Noise		

Export Tunnel Inspection Results Complete the Tunnel Inspection by saving results in two sharable formats. Share the profile with over under information as a PDF or CAD format.





#### 4 GENERAL APPLICATION IMPROVEMENTS AND FIXES

GNSS GS05 Smart Antenna	Tilt all day long using the GS05 Smart Antenna with tilt compensation and use Infinity for all data management and reporting needs including the post processing of static and kinematic observation campaigns.
IMAGING Create DSM & Orthophoto	Now its possible to use the sparse point cloud (SPC) from a stored orientation of an image group to generate a DSM and Orthophoto. This is helpful to produce a georeferenced overview of the project site in a short period of time. Note, using the dense point cloud (DPC) will produce the best orthophoto results and does take longer to process.
Export BricsCAD DWG	Simplify drafting workflows in BricsCAD v25 by using this DWG export to include additional measure and feature information. In BricsCAD use LEICACONVERT to create civil objects that include information such as code, attributes and point quality information to quickly and easily generate CAD drafting deliverables.
3D View	Navigating in projects that have high volume of data with point clouds, surfaces, orthophotos and CAD models is improved making it easier to select, rotate and zoom throughout the project data.
3D VIEW	Addressed the issue for displaying the kinematic track if some positions are not converted to grid after import, such as from a UAV.
FEATURES	Addressed the issue of creating a line feature from an existing point, the point code style settings were not being applied for the line style.
FEATURES	Addressed the issue when changing units in the project, the export settings were not being converted for Block Scaling.
TPS	Fixed an issue when check points were not visible from station setups that only have check point measurements.
TPS	Deleted points are now not available when using the Update Setups routine.
SURFACES	Fixed an issue when creating a Comparison Map using Horizontal Reference Plane the height was not being used from a selected height only point.
SERVICES	Added ability to set the EPSG code to be used with a WMS service



#### 5 WHAT IS NEW V4.2

- Create Material Surfaces from Tunnel Layers
- Point Cloud Classification
- Use Image Processing Templates with defined settings
- Create a quick-stitch image from a UAV drone flight
- Performance improvements working with large surfaces
- Project Features on to surfaces
- Extract B&W Targets after importing scanner data
- Match control points by geometry for scanner registration
- Improve display of adjustment results including display legend
- Undo/Redo includes a list of last operations
- Display status for user operations
- Support the Zeno Mobile 2.0 new Project structure
- Many quality improvements and bug fixes

#### **6** INFRASTRUCTURE MODULE

CREATE TUNNEL MATERIAL SURFACE



The ability to create material surfaces for a tunnel feature has been added. When a tunnel has more than one layer, it is possible to create material surfaces for each layer. By selecting the tunnel all layers will be created. Or choose a single layer to create a single material surface. The material surfaces can be shared with field software for scan, stake or check applications.



Road Material Surface



Creating material surfaces from road features includes performance improvements. Additionally, surfaces are now resolving cross slopes to a maximum vertical angle up or down from the last road element.





#### 7 POINT CLOUD REGISTRATION OPTION

REGISTER POINT CLOUDS	It is now possible to register point clouds that are imported from data sources other than a scan sensor, such as PTS or e57. Use registration to combine different point clouds from no Leica scan sensors or point clouds from third-party image processing software. Note: it is not possible to use Registration module to register image-processed point clouds. When a dense point cloud should be fitting to an existing point cloud the DPC (dense point cloud) processed from images must use common ground control points or scan targets to optimize the image group.
Extract Black & White Targets	Added ability to manually extract Black&White targets in the project. This supports the case when, on import, the automatic extraction of targets has not worked on all targets.
APPLY CONTROL BY GEOMETRY	Added option to automatically apply control points to targets by comparing the control points geometry with register targets geometry.
AUTO RENAME TARGET	When a target is renamed, all links using that target will also be renamed.
Scan Setup Properties	The properties for a scan setup now include information on the number of scan points and the sensor that captured the scan, including the serial number.

#### 8 POINT CLOUDS MODULE

POINT CLOUD CLASSIFICATION



Infinity projects now support point cloud classification. Users can assign class layers to a point cloud. Choose Manual Classification to open a panel that enables assigning a class layer to the selected area of the point cloud.

Importing and exporting point clouds with classes are supported when using one of these formats: LAS LAZ PLY.





CLASSIFICATION TABLES



Import or create a classification table that can be used to assign to a point cloud. By default, the standard LAS 1.4 classification table is assigned when creating a new project.

### 9 IMAGING MODULE

ΙΜΑ	GE PROCESSIN TEMPLATES	<ul> <li>Use Image Processing templates that include preferred settings for processing different image group acquisitions.</li> <li>Choose between 4 default templates which include suggested settings that support the type of image acquisition intended to be processed.</li> <li>Users can also create their own processing templates: Simply set the preferred settings for processing, and within the Image Processing settings window, select New Template from the template list.</li> </ul>
Proc	CESSING SETTI	NGS Added ability to choose different resolution settings for the Orientation step and the Dense Point Cloud step. Using different resolution settings can be used to reduce processing time.
PROCESSING SETTINGS Orientate		Added the option to enable or disable Compute Position Covariance when using Precise Mode for processing orientation of an image group. When this setting is used, the bundle adjustment is computing the Qxx matrix for each image pose position. This results in longer processing times, and improved data confidence applicable for filtering the point cloud using the Sigma Threshold setting. Precise Orientation lets users choose the more rigorous orientation processing option, reducing processing time by not using this setting.
		Note: Using Precise Mode for Orientation is recommended for GS18 I and hand- held terrestrial image acquisitions as well aerial drone surveys with low flight height and smaller gigapixel sizes. Using Fast Mode is recommended for general data acquisition flights and image groups with a large number of images.
Cre. FR	ATE DENSE PO OM CLEAN SPO	Users can select that sparse point cloud region that should be used to generate the dense point cloud. By selecting areas of the SPC and hiding points as desired, the DPC will be created from a reduced region. To reduce the SPC can be used to reduce processing time.



QUICK STITCH OVERVIEW IMAGE

🕸 Overview Image

A new option is available for generating an overview image that is quick to process and enables users to interpret project data quickly. This overview image is similar to the ortho photo, but it is not truly rectified and will contain artefacts.

Note: To achieve the best results, it is recommended to first process orientation and verify the data results of the image group before processing the overview image.

#### **10 FEATURES MODULE**

PROJECT FEATURE

Ъ Project 🛛

Added the ability to select a line or area feature to project onto a surface, point cloud or ortho image (including any base map image).

For example, importing a DXF file that includes a 2D polyline defining a boundary of a work site, but it is in 2D coordinates. Use this option to project the line on a surface feature in order to constrain the surface boundary to best compute a volume.



#### **11 SURFACES MODULE**

*PERFORMANCE IMPROVEMENTS* Working with large surfaces has been improved significantly. Users who generate digital surface models from UAV data and thus working with large surfaces, will find it much quicker to select and work with surfaces including operations to clean and compute differences between the different surfaces.

#### **12 GENERAL APPLICATION IMPROVEMENTS AND FIXES**

Network Adjustments	Added a scalebar in the graphic view to indicate the display of error ellipse and point reliability boxes.
Network Adjustments	Added a table in the report for coordinate residuals displayed N,E, Ortho Height
Network Adjustments	Added a table with a list of observations being excluded from the adjustment
Network Adjustments	Fixed the issue that when deleting the stored adjustment results the adjusted coordinates were not being removed



Undo Redo	Users can see the last 10 operations that were completed in the application and can select which point to perform the undo
USER OPERATIONS	Users can now see the operation they have performed on processing or editing events in the view strip of the application Modify Line succeeded
Import Zeno Projects	Added improved support for the latest Zeno Mobile application project files
Export BricsCAD DWG	Added the option to export project data in DWG format that includes additional feature information that can be visualized in BricsCAD. This improved DWG data flow will be available in the BricsCAD 2025 release and will include detailed steps that describe how to optimize this workflow.
COORDINATE SYSTEMS	Allow adding a height shift to the Compute Quick Ground coordinate system method.
TOTAL STATION PRISMS	Extended the default targets list to include the monitoring prisms GMP104, GPR112 and GMP004
Cogo Report	Added information to indicate for inverse measurements which height mode is shown in the report – Grid, Ground, Ellipsoidal.